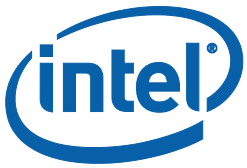

Apollo Lake Platform - Intel® Trusted Execution Engine (Intel® TXE) Firmware Bring-Up Guide

User Guide

August 2016

Revision 1.1

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Figures

Revision History

Revision Number	Description	Revision Date
0.5	• Initial release	September 2015
0.6	• Consolidated the two image creation procedure (SPI/eMMC) into one chapter. • MEU configuration was moved to the prerequisites section. • Update the DnX tool name to “dnxFwDownloader” and add the procedure to clear GPP4 prior to the image flashing. • Added a procedure to flash IFWI image onto SPI based platform using FPT. • Aligned to the latest FIT GUI. • Added SMIP configurations for SPI based platforms. • Added a section to set the platform SMIP according to the VR and Mod-Phy lanes. • Added Data clear security policy configurations. • Added Boot Guard 2.0 and TPM related configurations. • Added the IFP Emulation configurations. • Added the procedure the manually edit the platform SMIP according to the board configurations. • Added the phone flash tool DnX related command list in appendix C. • Added the procedure to set the “Quad enable” bit for SPI based platform in appendix D.	November 2015
0.7	• Updated the screenshot according to the latest tools UI. • Updated the “Flash Layout” configurations. • Added Platform SMIP default configurations for Intel® APL RVP. • In the platform protection configuration section, a procedure was added to create the necessary files for each boot guard profile.	December 2015
0.8	• Modified the SMIP configuration sections • Updated the guide according to the latest tool UI. • Updated the Boot Guard section, instructing the user to sign each of the components when choosing any profile. • Updated the pre-requisite image components table, removing the Intel TXE and PMC SMIPs. • Removed the appendixes for manually configuring the SMIP files, and boot guard legacy settings.	February 2016
0.85	• Add support for no-signing. • UI fixes.	March 2016

	• Removed ‘SPI Soft Strap Emulation’ IFP emulation from debug tab.	
0.9	• UI update. • Add the configuration for flexible BIOS data size and extended OBB.	May 2016
1.0	• UI fixes. • Remove BXT references. • Remove eMMC based platform configurations.	June 2016
1.1	• Removed Data clear security policy configurations • Added section 2.5 “Coinless Platform Configuration” • Removed reference to SPI read/write frequency recommendation	August 2016

§

1 Introduction

This document covers the Apollo Lake Platform Intel® Trusted Execution Engine (Intel® TXE) Firmware bring-up procedure.
Please notes that this guide only contains the SMIP configuration procedure for the critical boot settings, for the complete guide for the platform SMIP configurations please refer to “Broxton/Apollo Lake SoC SPI and SMIP programming guide (doc #559702).

1.1 Terminology

Term	Definition
APL	Apollo Lake. Braswell next generation platform
Intel® FIT	Intel® Flash Image Tool
MEU	Manifest Extension Utility
DnX	Download And Execute
SMIP	Signed Master Image Profile
ROT	Root Of Trust
ISS	Intel® Integrated Sensor Solution
GPIO	General Purpose Input/output
Intel® PTT	Intel® Platform Trusted Technology
IFWI	Integrated Firmware Image. The new Firmware image layout used in APL/BXT platforms
SPD	Storage Proxy Driver.
VR	Voltage Regulator.

§

2 Image Creation/Flashing Procedure

2.1 Prerequisites

2.1.1 IFWI Image Components, Tools and Drivers

In order to build the image the following image components are required:

Requirements	Require tool/component	Description
Tools	FIT	Flash image tool that is used to create the image.
	MEU	Manifest Extension Utility that is used to create manifests.
	OpenSSL	Freeware. Used to sign the manifests.
Image components (critical for platform boot)	IAFW (BIOS) SMIP Binary	Available in the BKC.
	PMC binary	Available in the PMC FW Kit.
	uCode patch 1	Available in the BKC.
	uCode patch 2	Available in the BKC.
	TXE FW binary	Available in TXE FW kit.
	ROT Key manifest	Available in TXE FW kit.
	OEM Key Manifest	Available in TXE FW kit or created using MEU
	Full IAFW(BIOS) binary	Generated by OEM/Available in the BKC.
Additional Image Components	iUnit binary	Available in the BKC.
	ISS image	Available in ISS Kit.
	ISS PDT File	Available in ISS Kit.

Requirements	Require tool/component	Description
Signing keys	Private key for SMIP signing	OEM generated, for more details please refer to the "BXT and APL Signing and Manifesting Guide" which is part of the TXE FW Kit.
	Private key for DnX signing	
Drivers	TXEI, SPD	Available in TXE FW kit.

2.1.2 MEU Configurations

2.1.2.1 Configuring MEU Signing Settings

FIT will use MEU in order to create the SMIP and DnX manifests (as part of the image creation process).Therefore, the signing settings will have to be configure in MEU prior to building the image.

Generate the MEU configuration file:

1. Run: MEU -gen meu_config

Edit the MEU configuration xml (meu_config.xml) which was created in the previous step, and set the following:

- "SigningToolPath" - path to the signing tool (the OpenSSL tool)
- "PrivatekeyPath" - path to the private key that used to sign the SMIP/DnX.

Figure 1 - MEU Configurations Example

```
<?xml version="1.0" encoding="utf-8"?>
<MeuConfig version="2.4" >
    <PathVars label="Path Variables">
        <WorkingDir value="./" label="$WorkingDir" help_text="Path for environment variable $WorkingDir" />
        <SourceDir value="./" label="$SourceDir" help_text="Path for environment variable $SourceDir" />
        <DestDir value="./" label="$DestDir" help_text="Path for environment variable $DestDir" />
        <UserVar1 value="./" label="$UserVar1" help_text="Path for environment variable $UserVar1" />
        <UserVar2 value="./" label="$UserVar2" help_text="Path for environment variable $UserVar2" />
        <UserVar3 value="./" label="$UserVar3" help_text="Path for environment variable $UserVar3" />
    </PathVars>
    <SigningConfig label="Signing Configuration">
        <SigningTool value="OpenSSL" value_list="Disabled,,OpenSSL,,MobileSigningUtil" label="Signing Tool"
        <SigningToolPath value="$SourceDir\Tools\MEU\openssl\openssl.exe" label="Signing Tool Path" help_te
        <PrivateKeyPath value="$SourceDir\Image_Components\Unofficial_samples\keys\bxt_dbg_priv_key.pem" lal
        <SigningToolXmlPath value="" label="Signing Tool Config XML Path" help_text="Configuration XML temp
        <SigningToolExecPath value="" label="Signing Tool Execution Path" help_text="Specify a directory fr
    </SigningConfig>
    <CompressionConfig label="Compression Configuration">
        <LzmaToolPath value="" label="LZMA Tool Path" help_text="Path to lzma tool executable." />
    </CompressionConfig>
</MeuConfig>
```

2.2 Flashing the ROM Bypass

For Broxton platform the ROM bypass needs to be flashed prior to the bring-up process, Please follow “Appendix A: ROM Bypass” to flash the ROM bypass image, before the image creation procedure.

2.3 Start FIT

Start the FIT tool by navigating to: \\Tools\FIT folder and running fit.exe

2.4 Creating the Binary Image

2.4.1 Configuring and Building the Image

Please follow the procedure below in order to configure and build the IFWI image.

2.4.1.1 Flash Layout Configurations:

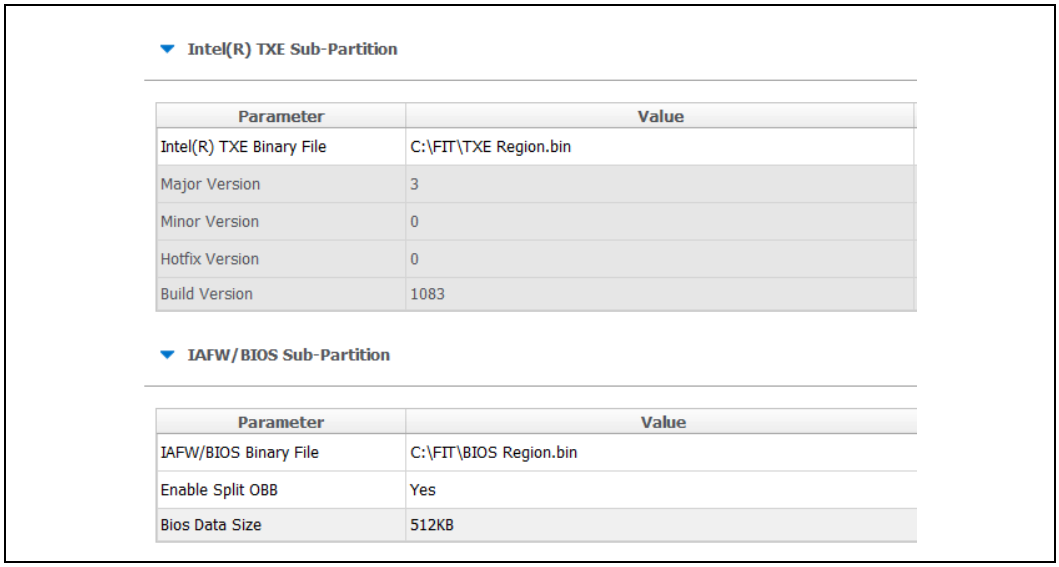
In the flash layout section in FIT, the following regions will be defined: TXE, BIOS, SMIP, iUnit, PMC, uCode.

Please note that the first region that needs to be configured is the TXE region since loading it will reset the existing image configurations.

1. Configure Intel TXE region:
    - On the left panel select the Flash layout tab
    - In the “Intel ® TXE Sub-Partition” set the following:
        - “Intel ® TXE Binary file”

2. Configure the BIOS region:
    - in Flash Layout tab, IA/BIOS Sub-Partition, configure:
        - “BIOS Binary File”
        - “Enable Split OBB” - enable this to extend the OBB into the LBP2 in order to accommodate for a larger OBB.
        - “BIOS Data Size” - configure the BIOS data size, this can be configured to ‘0’, ‘128KB’, ‘256KB’, ‘384KB’, 512KB’, this configuration will affect the maximum size of the OBB.

Figure 2. Intel® TXE and BIOS Region Configurations Example



3. Configuring the SMIP region:

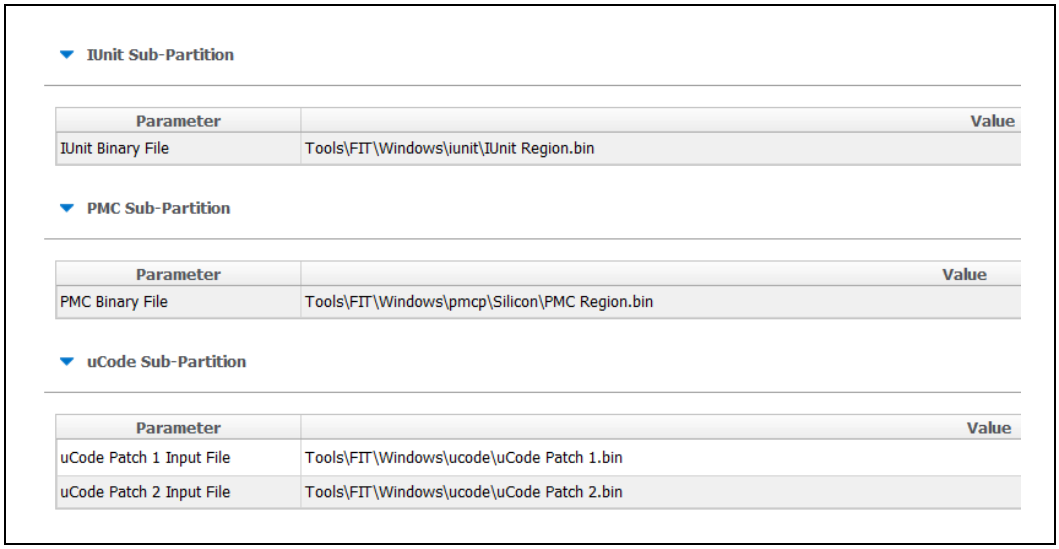
   - In the **flash layout** tab, **SMIP Sub-partition**, configure:
     - IAFW SMIP binary file (the BIOS SMIP).

Figure 3 - SMIP Configurations Example

4. Configuring the PMC and uCode regions:
   - in the **Flash layout** tab, **PMC Sub-Partition**, select:
     - PMC Binary file.
   - In the **Flash layout** tab, **uCode Sub-Partition**, select:
     - uCode patch 1 Input file.
     - uCode patch 2 Input file.

5. Configuring the iUnit (optional)
   - In the **Flash layout** tab, **iUnit Sub-Partition**, select:
     - iUnit Binary File.

Figure 4 - iUnit, PMC, uCode Configuration Example



IUnit Sub-Partition

Parameter	Value
IUnit Binary File	Tools\FIT\Windows\iunit\IUnit Region.bin

PMC Sub-Partition

Parameter	Value
PMC Binary File	Tools\FIT\Windows\pmcp\Silicon\PMC Region.bin

uCode Sub-Partition

Parameter	Value
uCode Patch 1 Input File	Tools\FIT\Windows\ucode\uCode Patch 1.bin
uCode Patch 2 Input File	Tools\FIT\Windows\ucode\uCode Patch 2.bin

2.4.1.2 Flash Settings Configurations:

In this section, the bootable device setting will be configured.

2.4.1.2.1 SPI Based Platform Configurations

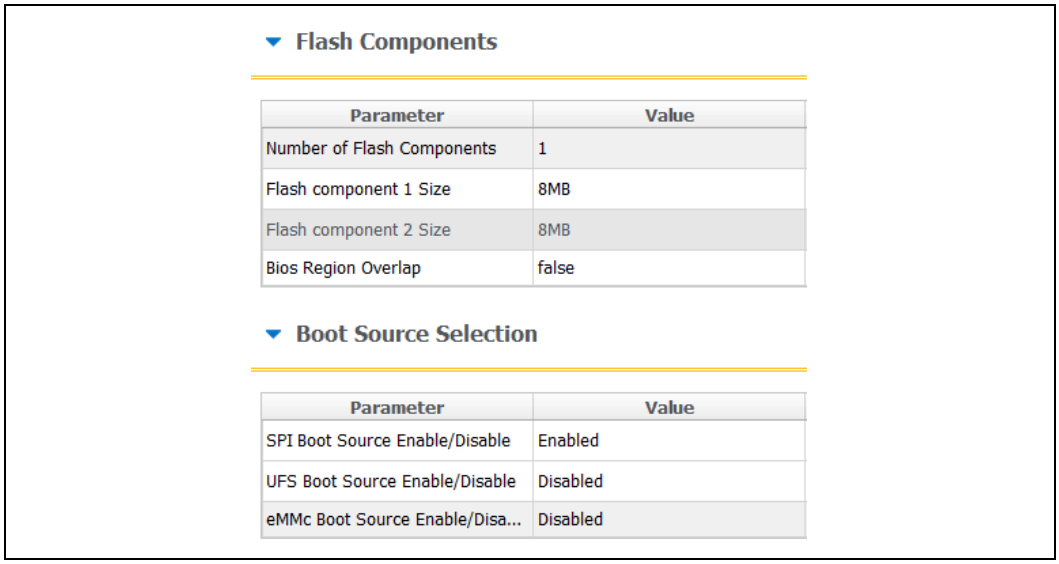
Under "**Flash Setting**" tab, "**flash component**" section set the following:

- "Number of Flash Components": should be configured to "1".
- Flash Component 1 size: should be configured to "8MB".
- BIOS region overlap: should be configured to "False".

Under "**Flash Setting**" tab, "**Boot Source Selection**" section, set the following:

- "SPI Boot Source Enable/Disable": should be set to "Enabled".
- "UFS Boot Source Enable/Disable": should be set to "Disabled".
- "eMMc Boot Source Enable/Disable": should be set to "Disabled".

Figure 5. SPI flash setting configuration example



Under "**Flash Setting**" tab, "**Flash Configuration**" section set the following according to the SPI flash part support:

- Boot Block Size - Enable per Top Swap usage on platform.
- Dual I/O Read Enabled
- Dual Output Fast Read Support
- Dual Output Read Enabled
- Fast Read Clock Frequency
- Fast Read Supported
- Quad I/O Read Enabled - please refer to the note below.
- Quad Output Read Enabled - please refer to the note below.
- Read ID and Read Status Clock Frequency
- Write and Erase Clock Frequency

Note: when setting "Quad I/O Read Enabled" or "Quad Output Read Enabled" to "Yes", the "Quad Enabled" bit need to be set in the SPI, without it the platform will **NOT BOOT**, please refer to "Appendix C: Enabling Quad mode on SPI Part" for the procedure.

Note: for detailed description of each configuration please refer to the "Apollo Lake SoC SPI and SMIP programming guide (doc #559702).

Figure 6 - APL RVP Flash Configuration Example

▼ Flash Configuration

Parameter	Value
Boot Block Size	64KB
Dual I/O Read Enabled	Yes
Dual Output Fast Read Supported	No
Dual Output Read Enabled	No
Fast Read clock frequency	40MHz
Fast Read supported	Yes
Invalid Instruction 0	0x00000021
Invalid Instruction 1	0x00000042
Invalid Instruction 2	0x00000060
Invalid Instruction 3	0x000000AD
Invalid Instruction 4	0x000000B7
Invalid Instruction 5	0x000000B9
Invalid Instruction 6	0x000000C4
Invalid Instruction 7	0x000000C7
PrrTopSwapOverride	No
Quad I/O Read Enabled	Yes
Quad Output Read Enabled	No
Read ID and Read Status clock frequency	40MHz
SpiStopPrefetchonFlushPending	No
SpiHostSwSequencingEnableDefault	No
SpiEnableDevice1DeepPowerdown	No
SpiEnableDevice2DeepPowerdown	No
SpiDelayBeforeRPMCBusyPollEnable	No
SpiDelayBeforeEraseBusyPollEnable	No
SpiDelayBeforeWriteBusyPollEnable	No
SpiIdletoDeepPowerDownTimeoutDefault	0x00000005
Write and Erase clock frequency	40MHz
WriteProtectionEnable	No
Protected Range Limit	0x00000000
ReadProtectionEnable	No
Protected Range Base	0x00000000

2.4.1.3 Platform SMIP Configurations

2.4.1.3.1 Voltage Regulator Depended SMIP Configurations

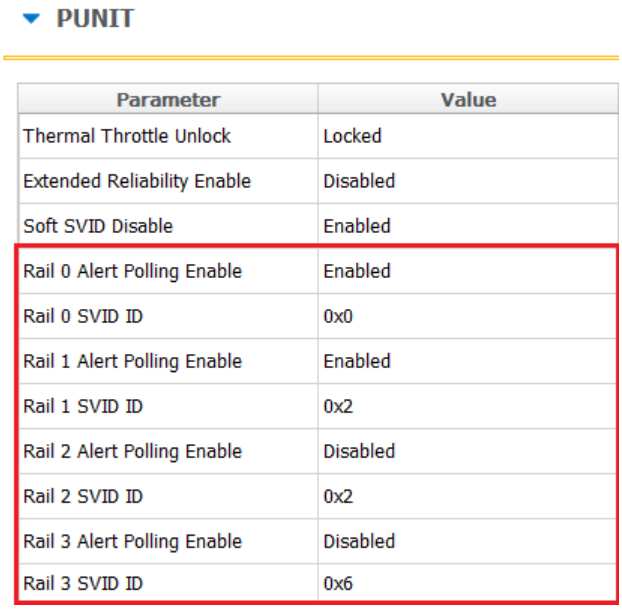
The following configurations needs to be set according to the VR of the board, for more information please refer to the “Broxton/Apollo Lake SoC SPI and SMIP programming guide (doc #559702).

In the "**CPU Straps**" tab, under "**PUNIT**" configure the following according to the board VR:

- Rail 0 Alert polling enable:
  - "Enabled" = SVID OR Whiskey Cove PMIC VR Type
  - "Disabled" = I2C VR Type
- Rail 0 SVID ID:
  - 0x0 = SVID OR I2C VR Type
  - 0x5 = Whiskey Cove PMIC VR Type
- Rail 1 Alert polling enable:
  - "Enabled" = SVID OR Whiskey Cove PMIC VR Type
  - "Disabled" = I2C VR Type
- Rail 1 SVID ID:
  - 0x0 = I2C VR Type
  - 0x1 = Whiskey Cove PMIC VR Type
  - 0x2 = SVID VR Type
- Rail 2 Alert polling enable:
  - "Enabled" = Whiskey Cove PMIC VR Type
  - "Disabled" = SVID OR I2C VR Type
- Rail 2 SVID ID:
  - 0x0 = SVID OR I2C VR Type
  - 0x2 = Whiskey Cove PMIC VR Type
- Rail 3 Alert polling enable:
  - "Enabled" = Whiskey Cove PMIC VR Type
  - "Disabled" = SVID OR I2C VR Type
- Rail 3 SVID ID:
  - 0x0 = I2C VR Type
  - 0x1 = SVID VR Type
  - 0x6 = Whiskey Cove PMIC VR Type

Note: Please refer to the example below for the APL Intel ® RVP configuration example.

Figure 7 - Configuration example according to APL Intel (R) RVP VR

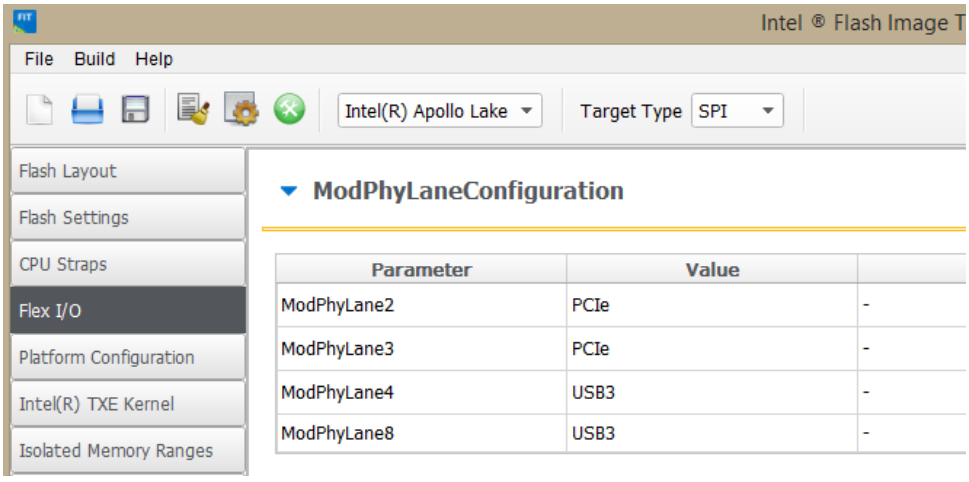


2.4.1.3.2 Mod-Phy lane Depended SMIP Configurations

The following configurations needs to be set according to the platform SMIP Mod-Phy lane configurations. Platform SMIP are fully configurable via FIT UI (XML or GUI). Refer to the relevant FIT tab/section for configuring SMIP. SPI and SMIP programming guide (part of TXE kit) has further details of each SMIP configuration.

Configure the Platform SMIP via FIT of the platform Mod-Phy configurations according to the screenshot below.

Figure 8 - Mod-Phy Lane Ownership FIT Configuration

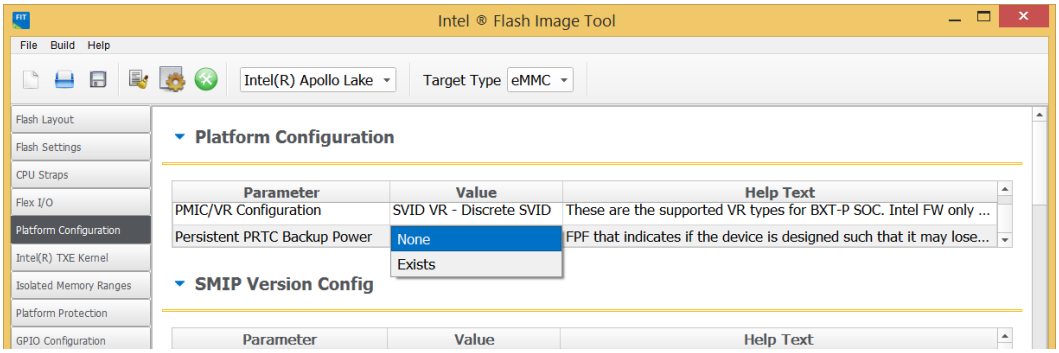


2.5 Coinless Platform Configuration

If your product design does not have Persistent RTC power (i.e. no coin battery), you may set the below configuration of "Persistent PRTC Backup Power" to "None" (Default is "Exists" = Coin Battery exists). Note that this configuration will be **permanently** set in FPF fuses and cannot be reversed. Setting this option, your system will lose some TXE features that depend on PRTC; like Anti-Replay Protection, PTT-Anti Hammering (PTT-AH), and DAL persistent time.

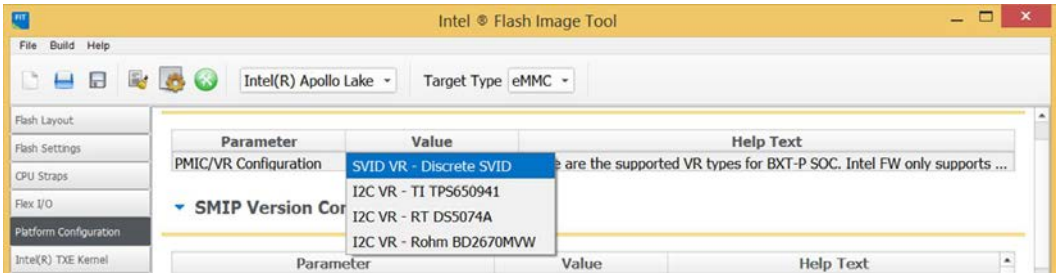
You may design your system in such a way to always guarantee power to RTC. See Apollo Lake Platform Design Guide (PDG) for more details.

Important: With "Persistent PRTC Backup Power = Exists", RTC power must not lose power 10 times in the lifetime of the product. PTT-AH feature uses RTC to detect physical attacks. PTT-AH counts RTC power loss in FPF to detect this. Once PTT-AH FPFs reach count 10, user will be locked out for 120 minutes when it boots. Every subsequent RTC power loss, user will also be locked out for 120 minutes. If you think your system, according to its design, will lose RTC power more than 10 times in its lifetime, then select "Persistent PRTC Backup Power = None" to avoid this lock out.



2.6 Voltage Regulator Configurations

When configuring customer platform with PMIC/VR setup (discrete SVIT/Rohm/RT/ TI), please use the below dropdown to make the selection:



2.6.1.1.1 PCIe SMIP Configurations

The Root Port Configurations needs to be set according to the platform schematics, for more information please refer to “Broxton/Apollo Lake SoC SPI and SMIP programming guide” (doc #559702).

In the “**Flex I/O**” tab under “**PCIe (x2)**” and **PCIE (x4)** sections set the “Root Port Configuration (RPCFG)” according to the platform schematics.

Figure 9 - APL Intel® RVP Root Port Configuration example

▼ PCIe (x2)

Parameter	Value
Root Port Configuration (RPCFG)	2x1
Lane Reversal (LNREV)	No
PCIe Port 0 Non-Common Clock...	Disabled
PCIe Port 1 Non-Common Clock...	Disabled
PCIe Port 2 Non-Common Clock...	Disabled
PCIe Port 3 Non-Common Clock...	Disabled

▼ PCIe (x4)

Parameter	Value
Root Port Configuration (RPCFG)	1x22x1
Lane Reversal (LNREV)	No
PCIe Port 4 Non-Common Clock...	Disabled
PCIe Port 5 Non-Common Clock...	Disabled

2.6.1.2 Platform Protection Configurations

2.6.1.2.1 Platform Integrity and Boot Guard Configurations

In this section the configurations that are related to the boot guard authentication flow will be set, these settings need to be aligned with the OEM Key manifest settings.

There are 3 available Boot Guard profiles:

- Boot Guard Profile 0 - Legacy: in this profile Boot Guard boot block verifications and measurement protection is off.
- Boot Guard Profile 1 - V: Strict Verification Enforcement. Prevents unverified bios components from running.
- Boot Guard Profile 1 - VM: Strict Verification and Measurement enforcement.

Prevents unverified Bios components from running.

When using the other Boot Guard profiles (Legacy/V/VM), and for complete information about signing and manifesting, please refer to the “BXT and APL Signing and Manifesting Guide” which is part of the FW Kit, please note that even when using “Boot Guard Profile 0 - Legacy” each component still needs to be manifested and signed.

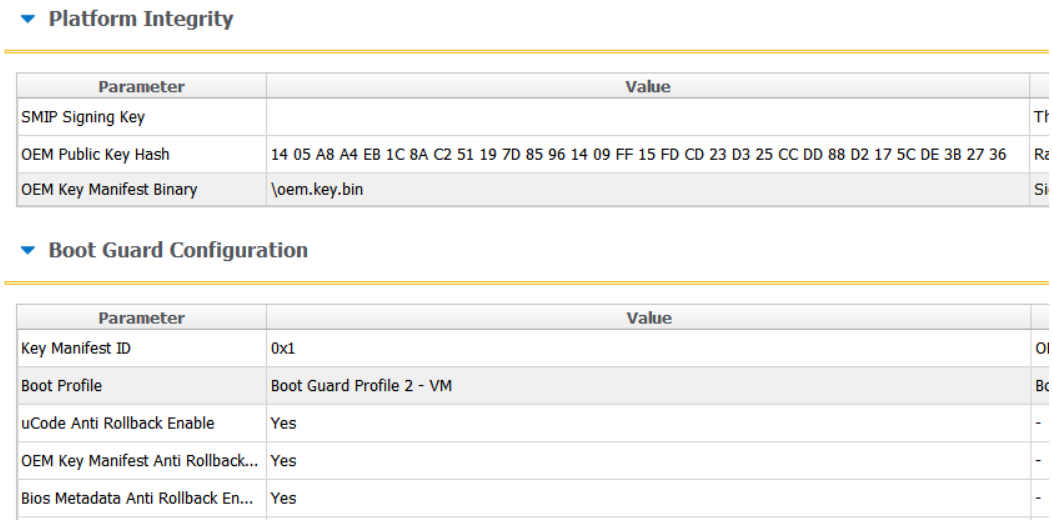
Note: when building an image for Intel® RVP, the required files for each of the boot guard profiles can be found in the TXE FW kit.

Once the necessary files were created according to the Boot Guard profile, in the “**platform protection**” tab, under “**Platform Integrity**” set:

- “SMIP Signing Key” - this will be the private key that will be used to sign the SMIP manifest, please note that as part of the OEM key manifest procedure, the SMIP public key (which is paired with this private key) will need to be configured for the SMIP manifest authentication.
- “OEM Public key Hash” - the hash of the public key that is used to authenticate the OEM key manifest.
- “OEM Key Manifest Binary” - the OEM Key manifest binary that was created using the MEU tool.
- “Key Manifest ID” - needs to be set according to the KMID in the OEM Key Manifest.
- “Boot Profile” - set to according to the boot guard profile.

When choosing not to sign the image, the above files does not need to be set, and ‘Boot Profile’ should be set to ‘Boot Guard profile 0 - legacy’.

Figure 10 - Platform Integrity and Boot Guard Configurations example



2.6.1.2.2 Intel® PTT and TPM Configurations

This settings needs to be set according to the TPM devices that is used on the platform.

When using fTPM the following configurations needs to be set:

- In the **platform protection** tab, under **Intel ® PTT configurations**, set:
  - Intel PTT initial power-up state to “Enable”.
  - Intel PTT Supported to “Yes”.
  - Intel PTT Supported [FPF] to “Yes”.
- In the **platform protection** tab, under **TPM Over SPI Bus Configurations**, set:
  - Discrete TPM Location to “None”.

When using a dTPM the following configurations needs to be set:

- In the **platform protection** tab, under **TPM Over SPI Bus Configurations**, set:
  - Discrete TPM location according to board configurations to SPI/LPC.

Figure 11 - TPM Configuration Example

▼ Intel (R) PTT Configuration

Parameter	Value
Intel(R) PTT initial power-up state	Enabled
Intel(R) PTT Supported	Yes
Intel(R) PTT Supported [FPF]	Yes

▼ TPM Over SPI Bus Configuration

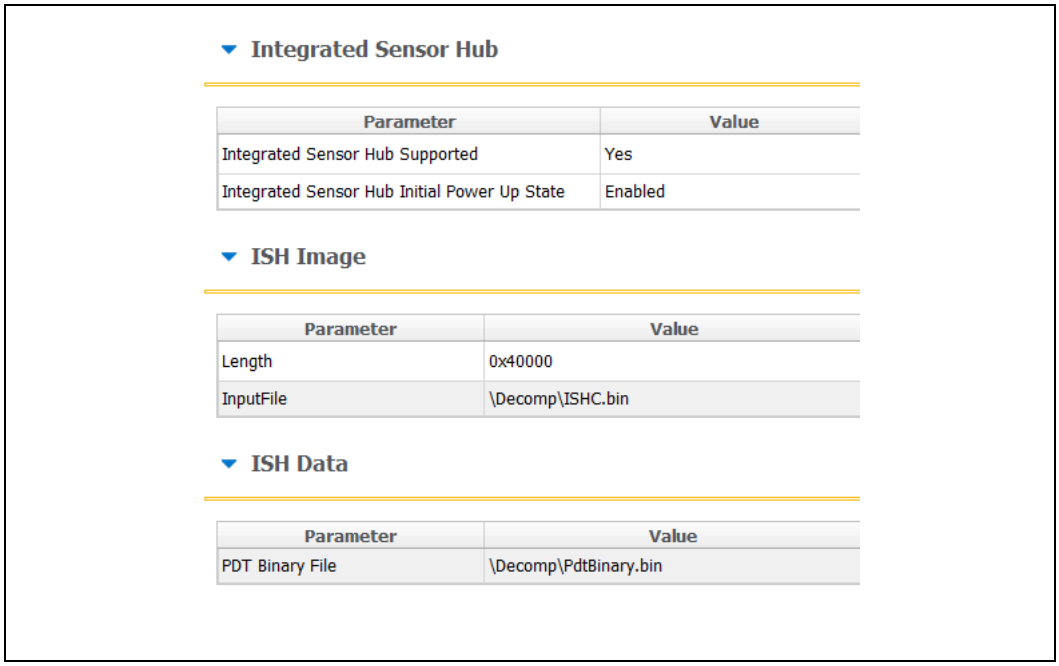
Parameter	Value
Discrete TPM Location	None
TPM Clock Frequency	17MHz

2.6.1.3 Intel® Integrated Sensor Solution Configurations

To enable Intel® Integrated Sensor Solution, the following configurations needs to be set in the “**Integrated Sensor Hub**” tab:

- Under “integrated Sensor Hub” section, set “Integrated Sensor Hub Supported” as “Yes”.
- Under “ISH Image” section, select the ISH binary location in “InputFile” field.
- Under “ISH Data” section, select the PDT file location in “PDT Binary File” field.

Figure 12. ISS Configurations example



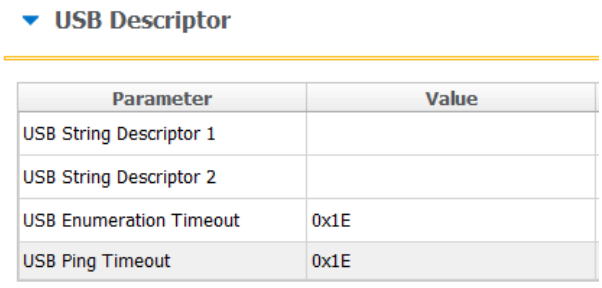
2.6.1.4 DnX Configurations

In this section the DnX (Download and Execute) settings will be configured, DnX is used to push tokens to the platforms.

For SPI based platform set:

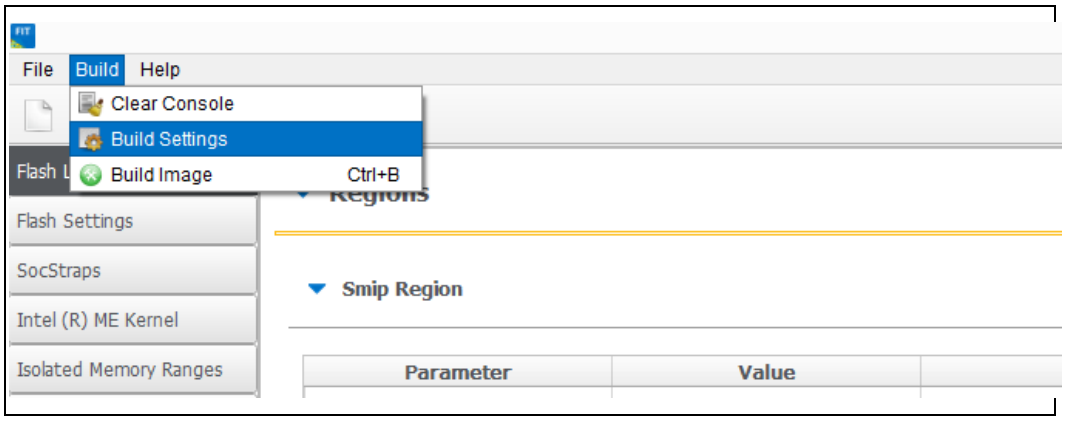
- Under the "**USB Descriptor**" section configure:
  - USB Enumeration Time-out - Time-out in SECONDS Used by ROM DnX logic to wait for enumeration from host before timing out. Default value is "0x1E" (30 seconds time out), to disable cable detection set this field to "0".
  - USB Ping Time-out - Time-out in SECONDS Used by ROM DnX logic to wait for ping from host before timing out. Default value is "0x1E" (30 seconds time out), to disable cable detection set this field to "0".

Figure 13 - USB Descriptor configuration example



2.6.2 Configuring Intel® FIT build settings

In the main menu select Build→ Build settings



Edit your configuration as shown below.

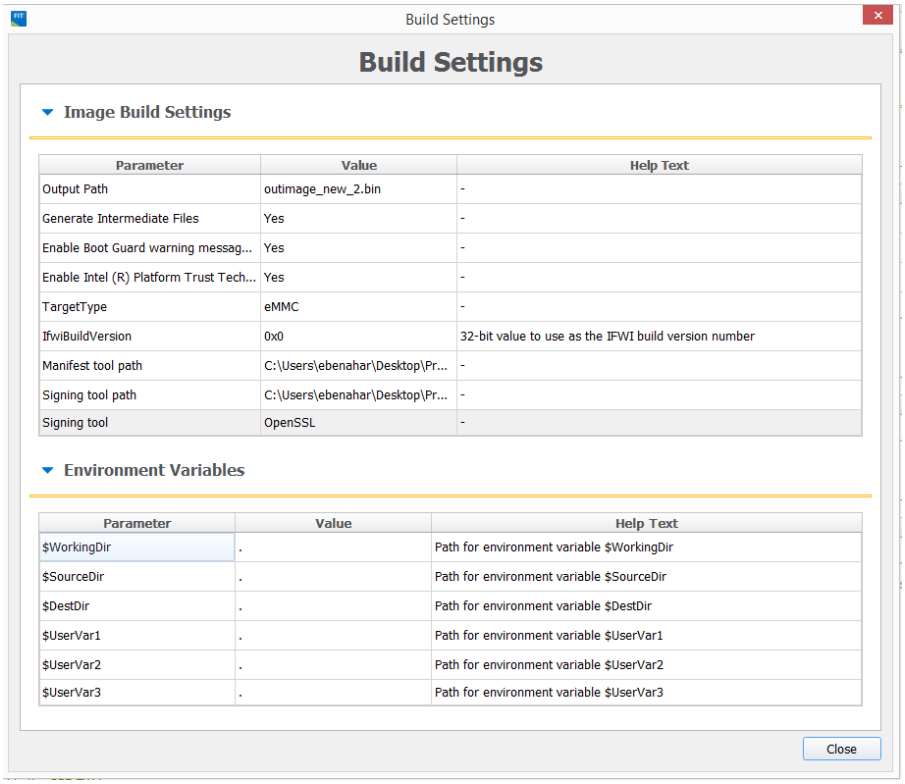
Image build setting:

- **Output path:** the location and name of the image that will be created.
- **Target Type:** the bootable device type SPI/eMMC/UFS.
- **Manifest tool path:** the path to the MEU tool.
- **Signing tool path:** the path to the signing tool.
- **Signing tool:** the signing tool that is going to be used.

Environment Variables: (optional)

- **$SourceDir:** The location where FIT will look for binary images during the image creation process.
- **$DestDir:** The location where FIT will save the binary image.

Figure 14 - Build configuration settings example

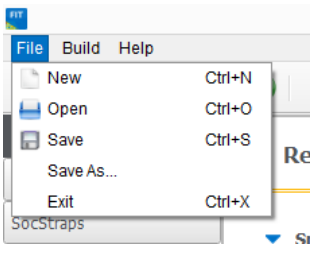


2.6.3 Save/Load Intel® FIT XML configuration

Once the IFWI setting have been configured, it's **highly** recommended to save these setting into a FIT xml, these settings can be loaded to simplify future image creations.

To save/load FIT configurations xml, from the FIT menu select: File → "open"/"save"/"save as".

Figure 15 - saving/loading Intel® FIT Configurations



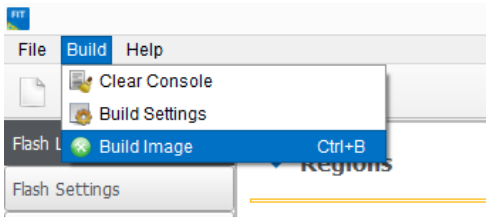
2.6.3.1 Building the Firmware Flash Image

Note: before building the FW image please make sure that the MEU setting are configured (procedure in the prerequisites section), without this the image creation, the process will **FAIL**.

After the IFWI configurations and the Build setting are set, build the image: FIT setting select build → "Build image".

The output will be the two images, one for DnX flashing (on eMMC based platform), and the other for external programmer/FPT flashing.

Figure 9 - Saving/Loading FIT Configurations



2.7 IFWI Flashing Procedure

2.7.1 Prerequisites

The following equipment and setup is required in order to complete IFWI flashing with DnX:

- Management console (a.k.a Recovery host). Can be any PC, running Windows 7/8.1 OS
- Recovery host should be connected to the target device (device being flashed) with a micro USB cable.
- Phone Flash Tool (PFT) should be installed on the recovery host. (Link to PFT location available in TXE kit Release Notes)
- DnX module (can be found in TXE kit) and the recovery image should be downloaded to the recovery host.
- eMMC needs to be selected as the boot source for the platform, on APL RVP set jumper J6E7 to 2-3.

2.8 Flashing Procedure for an SPI Based Platform

Please note that on APL Intel the boot source needs to be set as SPI, to do so set jumper J6E6 to 2-3.

2.8.1 Flashing an Image Using the FPT Tool

Flashing the SPI image can be done on the target platform from OS/EFI Shell using the Flash Programing Tool, the tool is located in the FW Kit under tools\Flash_Programming_tool.

To flash the image:

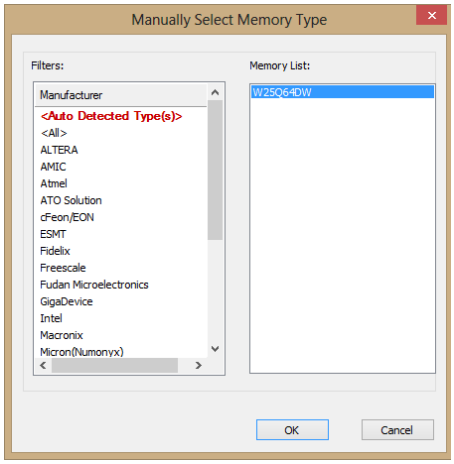
- Copy the FPT tool and the SPI image to the target platform
- From the FPT tool run: FPT -f “image_name.bin”

The expected output from the flashing procedure is “FPT Operation Passed”.

2.8.2 Flashing the Image Using Dediprog

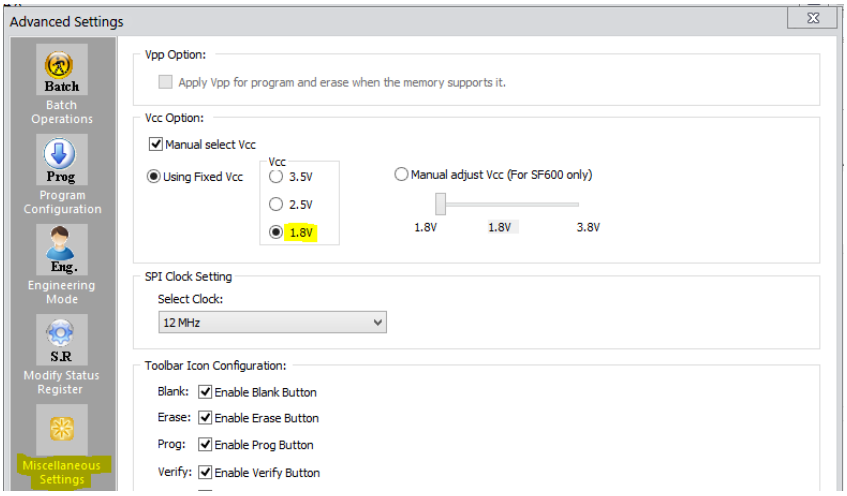
- Connect the Dediprog to the platform and run the Dediprog software.
- Click “Detect”.
- Under “Manually Select Memory Type” window, select the SPI flash and click OK

Figure 16 - Selecting the SPI Component



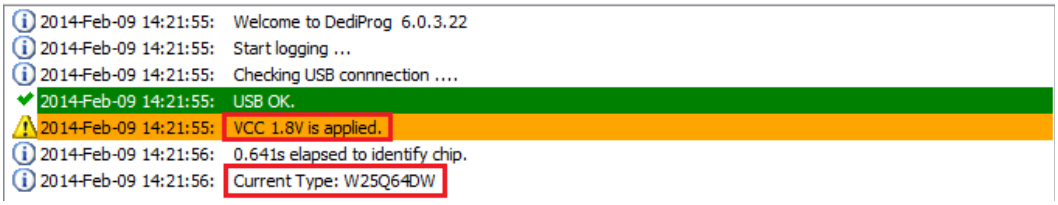
- Click: Config → Miscellaneous Settings, under “Vcc Option”, configure Vcc voltage to 1.8V.

Figure 17 - Set VCC Voltage



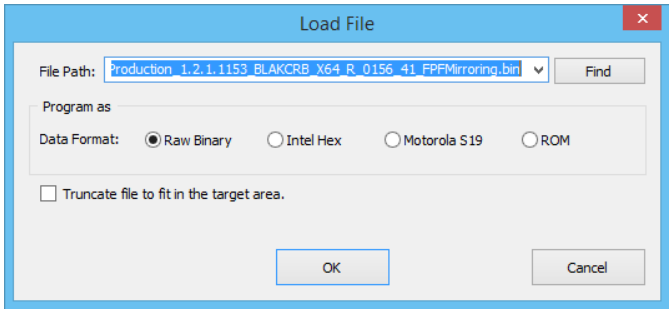
- Under DediProg main window, the VCC voltage will be set to 1.8V, and the SPI component will be selected.

Figure 18 - Main Window after the Configurations



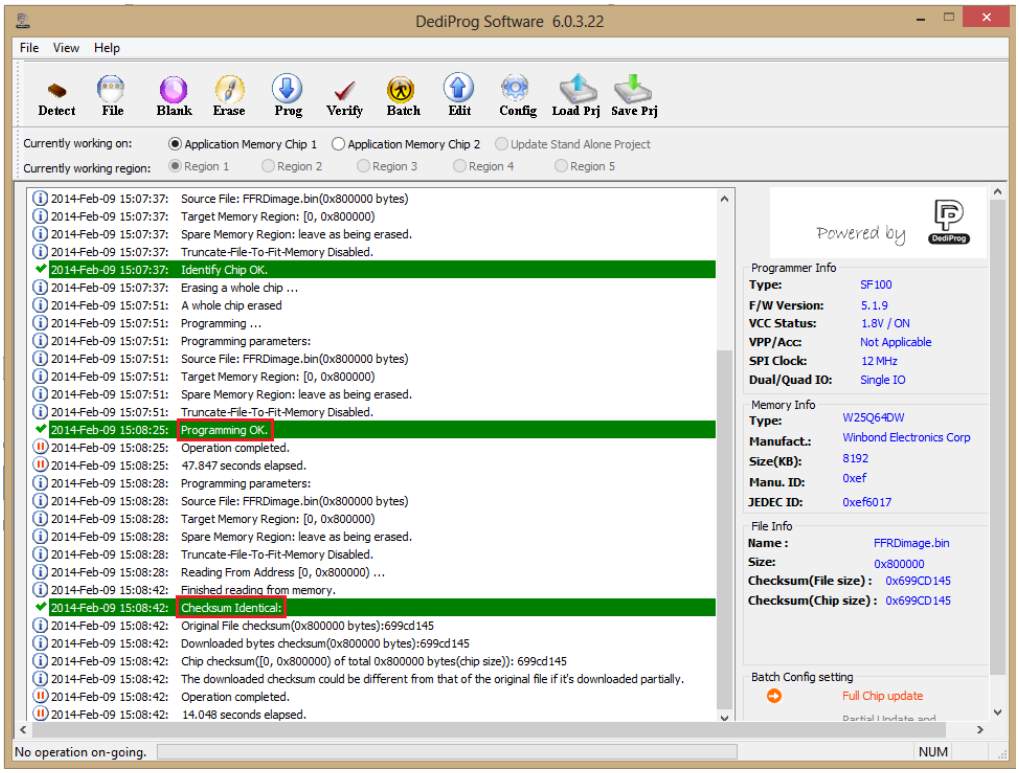
- Click “File”, select the SPI image that was built in section 2.4, “Creating the Binary Imag”.
- Under “Program as”, set data format as “Raw binary”.

Figure 19 - Load File Settings



- Click “Batch” to flash the file. When the procedure is over, click “Verify” to verify that the flashing was performed correctly.

Figure 20 - Flashing Procedure Expected Result



2.9 Windows Drivers Installation

Once the platform boots up to OS, install the TXEI and SPD using the SetupTXE.exe file that can be located in the kit under the “Installers” folder.

Note: the TXEI and SPD standalone drivers can be found under the same folder.

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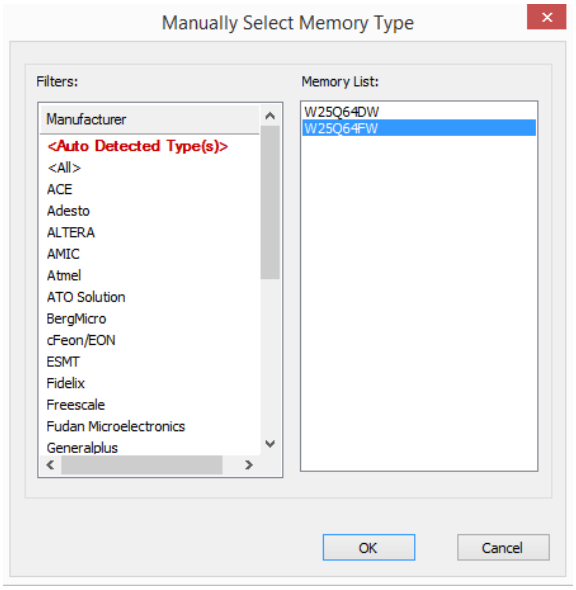
3 Appendix A: ROM Bypass

For BXT based platform ROM bypass needs to be flashed to the platform prior to the bring-up procedure.
The ROM bypass SPI image can be found in the TXE FW kit, under "Image_Components\TXE"

3.1 Flashing the ROM bypass

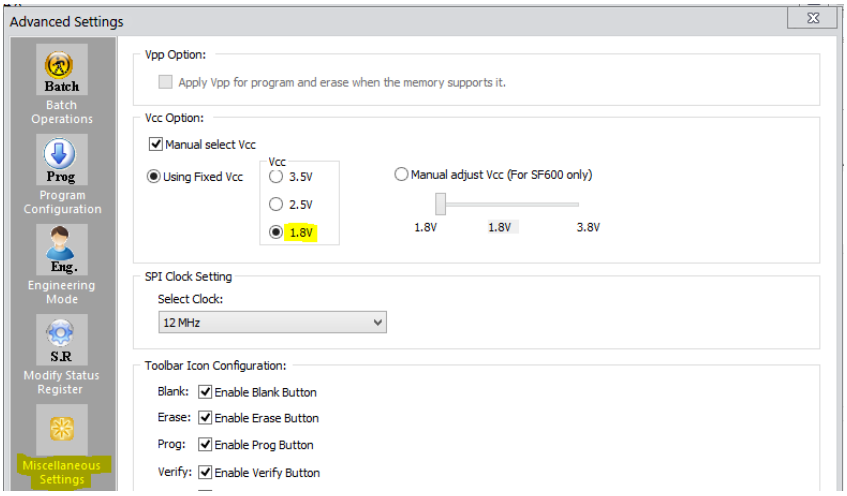
- Connect the Dediprog to the platform and run the Dediprog software.
- Click "Detect".
- In the "Manually Select Memory Type" window, select the SPI flash and click OK
  Note: on Intel RVP choose: "W25Q64FW"

Figure 21 - Selecting the SPI Component



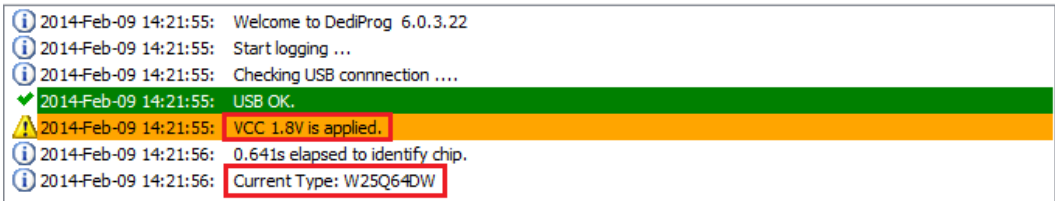
- Click: Config → Miscellaneous Settings, under "Vcc Option" configure Vcc voltage to 1.8V.

Figure 22 - Set VCC Voltage



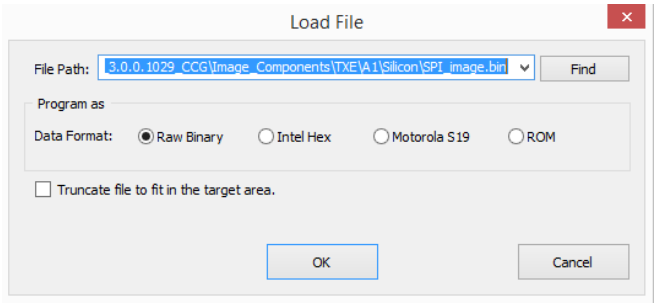
- In the DediProg main window the VCC voltage will be set to 1.8V, and the SPI component will be selected.

Figure 23 - Main Window after the Configurations



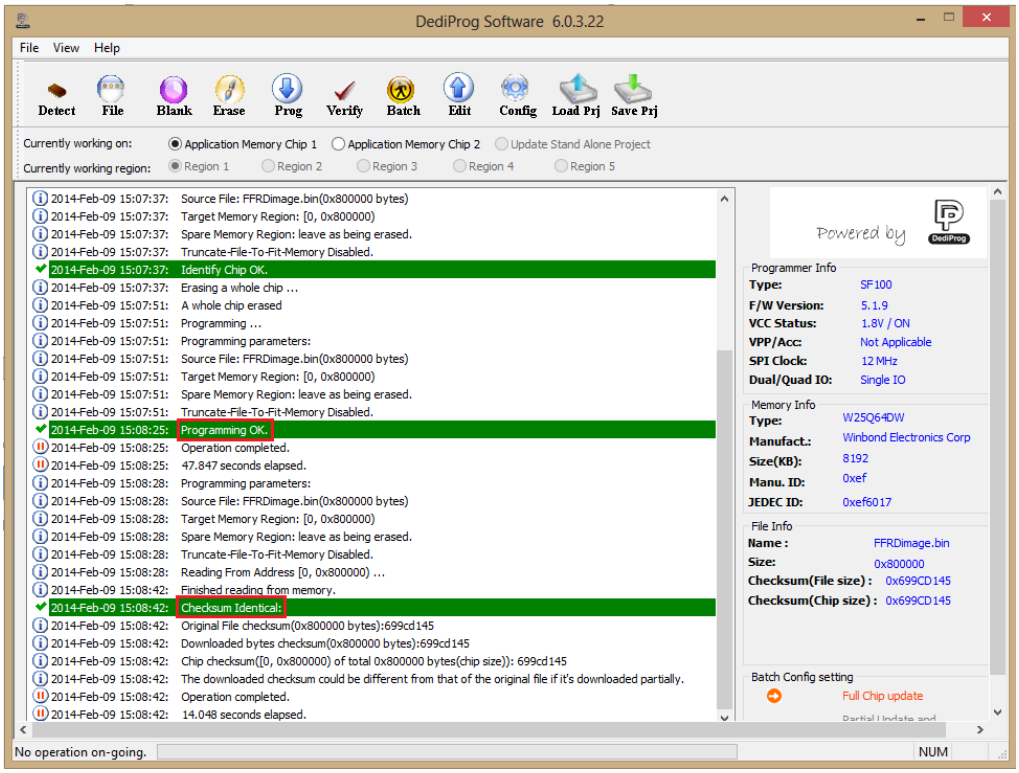
- Click “File”, select the SPI image that was built in section 2.4, “Creating the Binary Imag”. Under “Program as”, set data format as “Raw binary”.

Figure 24 - Load File Settings



- Click “Batch” to flash the file, when the procedure is over, click “Verify” to verify that the flashing was performed correctly.

Figure 25 - Flashing Procedure Expected Result



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4 Appendix B: Phone Flash Tool DnX Commands

Please refer to the table below for the Phone Flash Tool DnX related commands, please note that this commands needs to be run from a CLI.

Description	CLI command
Flashing IFWI image	dnxFwDownloader.exe --command downloadfwos --fw_dnx DNXP_0x1.bin --fw_image <IFWI_DnX_Image> --flags 0
Clear GPP4/RPMB	dnxFwDownloader.exe --command clearrpmb --fw_dnx DNXP_0x1.bin --device 2 --idx 0
Configure the GPPs on an eMMC based platform	dnxFwDownloader .exe --command configpart --fw_dnx DNXP_0x1.bin --path cfgpart.xml --device 2 --idx 0
Read token	dnxFwDownloader .exe --command readtoken --fw_dnx DNXP_0x1.bin --path read.bin --slot 0
Write token	dnxFwDownloader .exe --command writetoken --fw_dnx DNXP_0x1.bin --token test_token.bin --slot 0
Erase token	dnxFwDownloader .exe --command erasetoken --fw_dnx DNXP_0x1.bin --slot 0
Read boot media contents - EMMC BP1	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path boot1.bin --device 2 --idx 0 --start 0 --blocks 4096 --part 0
Read boot media contents - EMMC BP2	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path boot2.bin --device 2 --idx 0 --start 0 --blocks 4096 --part 1

Read boot media contents - EMMC GPP4	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path gpp4.bin --device 2 --idx 0 --start 0 --blocks 4096 --part 35
Read boot media contents - EMMC RPMB	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path rpmb.bin --device 2 --idx 0 --start 0 --blocks 4096 --part 16
Read boot media contents - UFS BP1	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path boot1.bin --device 3 --idx 0 --start 0 --blocks 4096 --part 0
Read boot media contents - UFS BP2	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path boot2.bin --device 3 --idx 0 --start 0 --blocks 4096 --part 1
Read boot media contents - UFS GPP4	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path gpp4.bin --device 3 --idx 0 --start 0 --blocks 4096 --part 22
Read boot media contents - UFS RPMB	dnxFwDownloader .exe --command readbootmedia --fw_dnx DNXP_0x1.bin --path rpmb.bin --device 3 --idx 0 --start 0 --blocks 4096 --part 48

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5 Appendix C: Enabling Quad Mode on SPI Part

When enabling quad operations in the soft steps the Quad enable bit needs to be set accordingly within the SPI part, if not the platform will not boot.

The Quad Enable bit location is different for each SPI vendor model, please refer to the SPI Spec in order to get the Quad Enabled bit location for your SPI device.

5.1 Setting the Quad Enabled Bit Using Dediprog

The following procedure uses the SPI part "MX25U6435FM2I-10G" as an example, please follow the procedure below with the settings that corresponds to the SPI device that is used on your platform.

Figure 26 - the Quad Enable information from the "MX25U6435FM2I-10G" SPI Spec

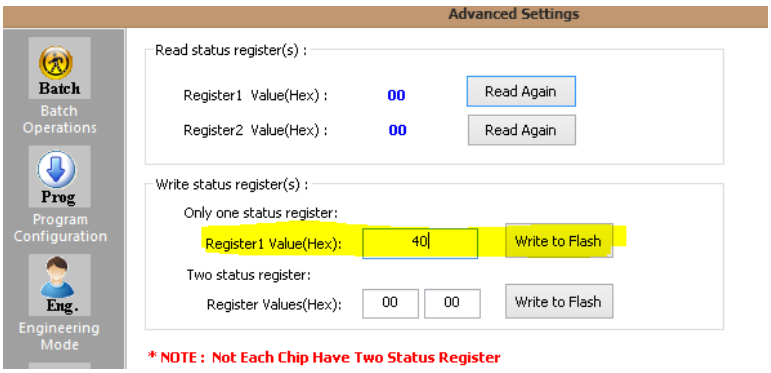
Status Register

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SRWD (status register write protect)	QE (Quad Enable)	BP3 (level of protected block)	BP2 (level of protected block)	BP1 (level of protected block)	BP0 (level of protected block)	WEL (write enable latch)	WIP (write in progress bit)
1=status register write disable	1=Quad Enable 0=not Quad Enable	(note 1)	(note 1)	(note 1)	(note 1)	1=write enable 0=not write enable	1=write operation 0=not in write operation
Non-volatile bit	Non-volatile bit	Non-volatile bit	Non-volatile bit	Non-volatile bit	Non-volatile bit	volatile bit	volatile bit

To set the Quad enable bit:

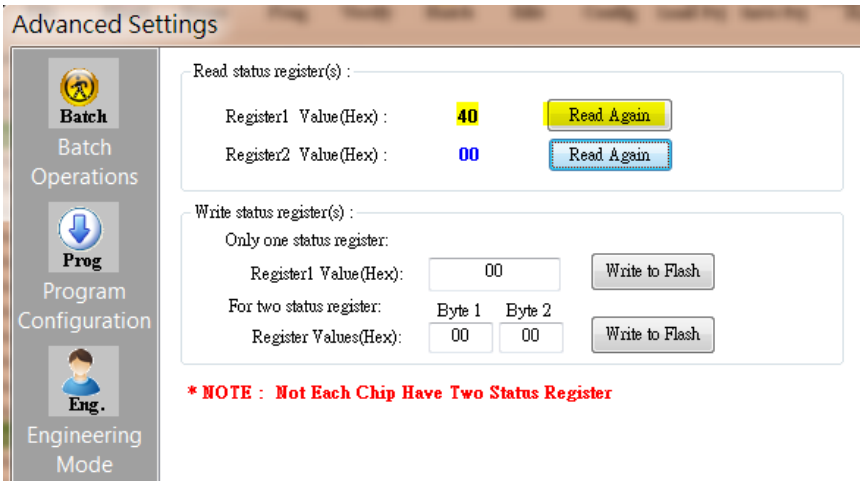
- Attached Dediprog to SPI device & open Dediprog Software
- Go to Config → S.R. Modify Status Register
- Under "Write Status register(s)", write "0x40" to "Register1 Value(Hex)" as shown below

Figure 27 - Writing the Quad Enable bit to the Flash



- Verify Register 1 has the value “40” as shown below

Figure 28 - verifying the register new value



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